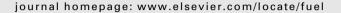


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Fuel





Optical characterization of Diesel and water emulsion fuel injection sprays using shadowgraphy



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HIGHLIGHTS

- Fuel injection sprays have been examined using a focused shadowgraph system.
- Diesel and Diesel and water emulsions containing 10% and 20% water examined.
- Temporal evolution of the spray cone angle and tip penetration have been measured.
- Emulsification reduced the cone angle at injection pressure of 500 bar.
- Emulsification had no discernable influence on the tip penetration.

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ABSTRACT

Diesel fuel and water emulsions have been shown to reduce emissions of NO_x and PM from compression ignition engines. There is a lack of work examining the influence of emulsification on the sprays formed during injection. This work examines the spray cone angle and tip penetration of Diesel fuel and water emulsions, containing 10% and 20% water (by mass). All experiments were conducted under non-reacting, non-vaporizing conditions in a constant volume pressure chamber filled with nitrogen. A focused shadowgraph system, with high speed photography, coupled with a research, high current LED system was used. Differences in the spray cone angle suggest the emulsification did have an effect for the injections at a pressure of 500 bar. Emulsification had no discernible effect on the spray tip penetration. Spray tip penetration showed agreement with previous trends in terms of proportionality to time after start of injection however agreement with models found in the literature was not consistent.

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1. Introduction

The use of the internal combustion engine is accompanied by the emission of a range of combustion products into the atmosphere. The legislation of these emissions has become more stringent in previous years as the understanding and concern about environmental pollution has drastically increased [1]. Of particular concern are the emissions of soot, particulate matter (PM) and nitrogen oxides (NO_x) [2]. This paper focuses on a Diesel fuel additive in the form of water to create Diesel fuel and water emulsions (Diesel fuel emulsions from here). Such emulsions have shown the potential to assist in the control of these emissions from a compression ignition (CI) engine [3].

1.1. Emulsions

A Diesel fuel emulsion is a mixture of the base fuel (Diesel), defined as the oil or continues phase, with water, the dispersed phase. Water is added to the Diesel fuel in the range of 10–30% by mass or volume. A small amount of surfactant, usually in the range 1–5% is used to stabilize the emulsion. A surfactant is a substance that is adsorbed at the interface of the system and alters the inter-facial free energy of the interface. The Diesel fuel emulsion is then utilized in the CI engine as normal. The use of Diesel fuel emulsions has been shown to reduce NO_x, CO, soot, hydrocarbons (HC) and PM emissions when used in a CI engine [3–10]. Diesel fuel emulsions have also been shown to slightly improve the brake thermal efficiency of a CI engine [8,10–12].

There has been very little work done investigating the spray characteristics of Diesel fuel emulsions, which contributes to a

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$ \begin{array}{lll} A & {\rm triangle~area} \\ C & {\rm empirical~constant} \\ \rho_f & {\rm fuel~density} \\ \rho_a & {\rm ambient~density} \\ {\rm CO} & {\rm carbon~monoxide} \\ {\rm HC} & {\rm hydrocarbon} \\ {\rm NO}_x & {\rm nitrogen~oxides} \\ P & {\rm pressure} \\ {\rm PM} & {\rm particulate~matter} \\ S & {\rm spray~tip~penetration} \\ t & {\rm time} \\ \theta & {\rm spray~cone~angle} \\ \end{array} $	Abbreviations CI compression ignition DAQ data acquisition EOI end of injection HLB hydrophilic-lipophilic balance ICE internal combustion engine SOI start of injection TTL transistor transistor logic
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general lack of understanding concerning their use in direct injection CI engines. This study goes some way to address this through the optical characterization of Diesel fuel emulsion sprays. The primary break-up of the spray has been considered with secondary break-up not considered. For this aim the spray parameters used to characterize the sprays is the spray cone angle and the spray tip penetration.

1.2. Characterization of fuel sprays

The primary break-up of fuel injection sprays is difficult to characterize using conventional optical measurement techniques (such as the phase Doppler technique or PIV) due to the density of the spray in that region. Hence spray cone angle and tip penetration, which can be obtained using photographic techniques, are among the most frequently reported parameters in fuel-spray research [13]. Schlieren and shadowgraphy are two related techniques used to visualize the spatial variation of density in a transparent medium, which in most cases is a gas (e.g. air). Both techniques have previously been utilized, in various forms, to examine and characterize fuel injection spray parameters [14–18].

Previous experimentation has found that the spray cone angle depends on the density of the ambient atmosphere into which the spray emanates, with models based upon experimental work commonly taking the form [19–21]

$$\theta = \propto \left(\frac{\rho_a}{\rho_f}\right)^a \tag{1}$$

where ρ_a is the ambient density, ρ_f is the fuel density and a is an experimentally derived constant. Such models show θ to be a function of the ratio of liquid and gas densities (ρ_a/ρ_f) , not the injection velocity (hence injection pressure). The work [21] includes a review of the relationship between spray cone angle and the density ratio as well as experimental findings and reports a = 0.19, with no significant influence from the injection pressure.

In much of the previous work, the temporal development of the spray cone is ignored [16], with experimental fits to proposed models taken from the quasi-steady/constant period of spray cone angle. Table 1 shows some spray cone angles (from the period of constant value) and the time after SOI when the angle is observed to become constant (transition time) that have been presented in previous works. Considering that the time involved for the spray to reach its quasi-steady angle is of the same order as a typical ignition delay period in a CI engine, any influence on mixing may be overlooked.

The temporal development of the spray tip penetration into the combustion chamber has been examined for a number of years. The most widely excepted findings and developed correlations

come from the work of Hiroyasu and Arai [20] which is still used for comparison purposes in current work [16,28,29]. In [20], two distinct periods of tip development were identified. An early stage of the spray development where $S \propto t$ followed by a transition to a period where $S \propto t^{1/2}$. The spray velocity during the early period is modeled as constant and spray develops as a steady jet. The time when the transition occurs is described as the breakup time which was shown to decrease with increasing injection pressure. The Hiroyasu and Arai model is often presented in the form

$$0 < t < t_{break} \quad S(t) = 0.39 \sqrt{\frac{2\Delta P}{\rho_f}} t \tag{2}$$

$$t \geqslant t_{break}$$
 $S(t) = 2.95 \left(\frac{\Delta P}{\rho_a}\right)^{\frac{1}{4}} \sqrt{d_0 t}$ (3)

where,
$$t_{break} = \frac{29\rho_f d_n}{(\rho_\sigma \Delta P)^{\frac{1}{2}}}$$
 (4)

The reason behind the discontinuity between the two periods has not always been accepted, though the linear relationship during the early period has been accepted for many years. Hiroyasu and Arai [20] describe the spray as not fully atomized resulting in a penetration with a constant velocity, hence the transition time is the time where breakup occurs. Nabers and Siebers [21] described the transition time as the time where the spray is dominated by injected liquid being dominated by entrained gas.

The linearity of the initial stage has come into question in some recent studies [15]. The instant the injector opens, the spray jet velocity must be zero, an infinitesimal period of time later a sharp rise in spray jet velocity must occur (acceleration) hence the linearity of the initial period does not make physical sense [29]. With this in mind, the work [29] developed an empirical model from an experimental campaign conducted at a much higher temporal resolution than most other work and specifically investigated the early period of spray evolution. The model is in the form

Table 1Spray cone angles and transition times observed in previous studies.

Previous study	$ heta^{\circ}$	Transition time (μs)
[15]	30	1000
[16]	20	400
[21]	20	500
[22]	15-20	600
[23]	20	300
[24]	15	1000-1200
[25]	10-18	150
[26,27]	-	300

$$S(t) = Ct^{3/2} \tag{5}$$

where C is an empirically fitted constant and no physical explanation is attempted to derive or explain the relationship. Upon differentiating, the spray tip velocity, U, is proportional to $t^{0.5}$, which is not ill defined as t approaches zero [29]. The Kostas findings appear to be more physically realistic but also show poor agreement with the Hiroyasu model.

The work [16] builds upon the findings presented in [29]. An empirical relationship of injection parameters and the initial period to determine the values of *A* are presented in the form

$$S(t) = \left(\frac{\rho_f}{\rho_g}\right)^{0.25} \left(\frac{\rho_g^{1/3} \Delta P}{12\rho_f}\right)^{0.5} t^{3/2}$$
 (6)

In the work [29] the penetration after the t_{break} is considered to be the same as in the Hiroyasu model while [16] introduced a nozzle conicity term to take into account any cavitation effects in the form

$$S(t) = 2.95 \left(\frac{\Delta P}{\rho_a}\right)^{0.25} \sqrt{\left(C_f\right)^2 d_o t} fort \geqslant t_{break}, \quad C_f = \frac{d_i}{d_o}$$
 (7)

where d_i is the inlet diameter and d_o is the outlet diameter of the nozzle.

Whilst engine testing of emulsified fuels is widely published, fundamental spray experiments are rare. The work [30] is partially concerned with the spray parameters of Diesel fuel emulsions. An emulsion containing 10% water is injected into a constant volume combustion chamber, under reactive, vaporizing conditions (air at 830 K), with the cone angle measured at 42 and 112 nozzle diameters downstream of the nozzle. The emulsion fuel droplets and ligaments (not tip penetration) were observed to penetrate further than with pure Diesel fuel. The cone angles were observed to be very similar for each fuel. No conclusions concerning the fundamental nature of the spray parameters were made.

The works [31,32] were conducted in a constant volume, precombustion chamber at 800 and 1200 K under reactive conditions. The emulsions examined were 10% and 20% water produced in a homogenizer, injection pressure was 70 MPa. A longer tip penetration for the emulsions and a thickened spray at the beginning of the injection period was observed. This is stated to be due to the higher viscosity and surface tension of the emulsions. At the 1200 K temperature, the tip penetrations for the Diesel and the emulsions were similar.

2. Experimental set-up

2.1. High pressure chamber design

All tests were conducted in a stainless steel high pressure chamber with optical access. The chamber was charged with nitrogen at the ambient temperature of 20 °C. Two chamber pressures were considered, 20 and 30 bar, corresponding to two ambient gas densities of 22.6 kg/m³ and 34.5 kg/m³ respectively. Maximum observable length of spray was in the region of 60 mm. Window fouling was avoided using a solenoid valve that opened for a short duration after an injection, purging the chamber of the injected fuel. It took approximately 2 min after purging for the chamber to return to the corresponding pressure and temperature. Fuel injection was by means of a research, high pressure common rail system. The injector was an asymmetric, seven hole, piezo actuated Siemens mini-sac type. Due to the arrangement of the nozzle holes, it was necessary to block all but one hole to allow single spray examination. The holes were blocked by laser welding using a jewelers welding rig. The common rail pressure was measured by a pressure transducer fitted in the rail and was taken to be the injection pressure. The high pressure pump was a double ended hydraulic type (Sprague P4333), driven by compressed air capable of supplying fuel to the rail at up to 200 MPa. The outlet pressure was controlled via the compressed air inlet pressure, once this was set at the regulator, no adjustment or control was required to maintain the outlet pressure. The injector was controlled by a Hartridge HK853 driver which was triggered from a TTL signal controlled from a custom LabView program.

2.2. Optical arrangement

A double pass, single mirror schlieren/shadowgraph system using a high power LED provided the optical diagnostic. The mirror is a spherical, concave 101 mm diameter with focal length of 1219 mm, f/12, mounted into a positioning mechanism. The mirror was placed as close as possible to the back window of the chamber. The point light source was placed a distance of two focal lengths from the center of the mirror. The light source is discussed in detail in Section 2.3.

The light returning from the mirror was diverted into the camera lens by a 50/50 beamsplitter which was mounted at a distance of 2133 mm from the mirror. The Phantom v7.11 camera was positioned with a 200 mm lens (aperture set to f/11) at a distance of approximately 51 mm from this focal point. The camera was operated with a resolution of 256×256 pixels, with an camera exposure time of $33.25~\mu s$. Maximum frame rate at this resolution was 30,075 frames per second. A schematic of the system is shown in Fig. 1. The camera was triggered by the same TTL which triggered the injector driver, whilst the image sequences were recorded on a dedicated camera computer.

2.3. L.E.D illumination system

In order to achieve suitable images at the frame rate desired, a high intensity, short duration light source was required. At 30,075 fps, maximum exposure time is approximately 30 μs . This length of exposure is too long to "freeze" the spray to produce images with well defined, sharp edges and tips. Exposure times in the region of 1–10 μs were found to be ideal for this purpose.

A pulsed, overdriven current LED system based upon the work in [33–38] was developed for use in this study. The system consisted of a high power, green Phatlight CBT-40 LED [39] which is rated to operate with a current of 5.9 A continuous or 9.8 A pulsed (50% duty cycle). The LED was controlled by a circuit consisting of a bank of capacitors which were charged by the supply voltage, 30 V in this study. The capacitors discharge through the LED, switched by a MOSFET power transistor with TTL compatible input. Current through the LED was determined by measuring the voltage across a resistor on the MOSFET ground side with an oscilloscope. The LED pulse was controlled by the TTL input to the MOSFET, which is generated by a LabView program running on the DAQ PC. The LED period was set at 33.25 μ s, to match the cameras frame rate. The pulse width (time when LED is on) was set to 3 μ s, hence the effective exposure time was 3 μ s.

With these settings, the current through the LED was approximately 60 A. In the work [37] this same LED was shown to increase in light emission with increasing drive current with a proportionality of approximately 0.35 beyond currents of 10 A. Using the 0.35 proportionality, the increase in current from 9.8 A to the 60 A used in this study will result in an effective pulse power of 21 W. Fine tuning of camera and LED syncing was possible by inducing a small delay in the camera from the trigger to account for any discrepancies between the LabView clock and the camera clock and any lag induced in the system. The LED system performed extremely well, was low cost and avoided many of the health and safety issues that are imposed when using lasers.

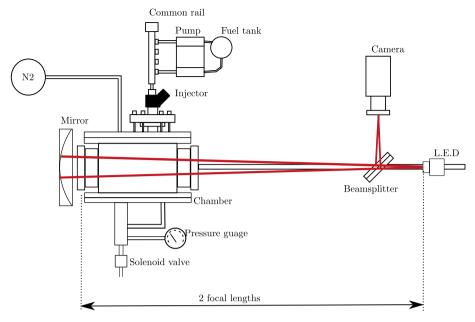


Fig. 1. Schematic of the focused shadowgraph system used with the high pressure chamber.

2.3.1. Emulsion production

The Diesel fuel emulsions were made using standard pump Diesel fuel with the addition of 10% and 20% of water (by mass). The choice of suitable surfactant was made using the hydrophilic-lipophilic balance (HLB) methodology and results of previous studies [5,11,31,40,41]. The two surfactants used were Span 80, a nonionic lipophilic surfactant with a HLB of 4.3 and Tween 80, a non-ionic hydrophilic surfactant with a HLB of 15. It was found that the surfactant mix resulting in a HLB of approximately 6.4 (80% Span 80 and 20% Tween 80) resulted in the most stable emulsion [42]. It has been seen in studies elsewhere [40,43] that the use of mixture of Span 80 and Tween 80 leads to better results compared with the use of a single surfactant with equivalent value of HLB. The emulsion was produced by ultrasonic mixing using an ultrasound generator (Sonics, Vibra-cell 750 W, 20 kHz) and a ultrasonic probe (Model CV33). The ultrasonic method of mixing has been used elsewhere [4,44-46] and has been shown to result in: smaller mean droplet size; larger number of water droplets that are distributed more uniformly in the continuous phase; lower separating rates of the water droplets from the emulsions when compared with emulsions prepared by a more conventional mechanical homogenizer [4]. Ultrasonic emulsification is therefore recognized as a fast, efficient technique for producing tiny and uniformly-sized droplets.

2.4. Fuel densities and viscosity

The density and viscosity for each fuel has also been determined and are presented in Table 2. For all cases the viscosity was observed to reach a constant when the shear rate was between $400 \text{ and } 1000 \text{ s}^{-1}$. The mean value presented is the determined

Table 2Fuel density and viscosity.

Diesel 814 0.00588 Diesel 10/% water 829 0.00669 Diesel 20/% water 876 0.00678	Fuel	Density (kg/m³)	Viscosity (Pa s)
Diesei 20/8 water 0.00070		***	

from taking the mean value of this constant period. The measurement was repeated three times and these 3 mean values were used to obtain a mean viscosity of the fuels, stated in Pascal seconds.

2.4.1. Image processing

All images were processed using a piece of Matlab script produced by the authors. The image processing is discussed in detail in [47]. The image analysis makes use of the Otsu method to determine global threshold levels (Matlab *graythresh*) and is independent of any user defined inputs. No image adjustments where made, with the original pixel values and image histogram used for the analysis. The spray tip was defined as the last spray signal along the spray central axis downstream from the nozzle. Spray cone angle was determined using the triangle technique introduced in the work [21] and also utilized in [25,48,49]. The angle corresponds to that of a triangle whose area is equal to the projected area of the upstream half of the spray. The angle θ is given by

$$\theta = 2 \tan^{-1} \left(\frac{A}{(S/2)^2} \right) \tag{8}$$

where A is the projected area of the upstream half of the spray, S/2 is half of the tip penetration.

3. Results and discussion

3.1. Spray cone angle

Fig. 2 shows an example image of a fuel spray collected using the shadowgraph system complete with the image processing stages used to determine the spray cone angle, θ_S and the tip penetration, S_S (subscript s for shadowgraph). In Fig. 2 a Diesel spray is shown as it is approaching it's quasi-steady, quasi-constant θ_S period, 1064 μ s after SOI. Sequences of images collected like that shown in Fig. 2 were used to determine the temporal evolution of the spray angle and tip penetration for each fuel tested.

Figs. 3 and 4 show the temporal evolution of $\theta_{\rm S}$ for Diesel fuel, D10 and D20 at the two ambient densities into which the injection took place; 22.6 kg/m³ (P_{amb} = 20 bar) and 34.5 kg/m³

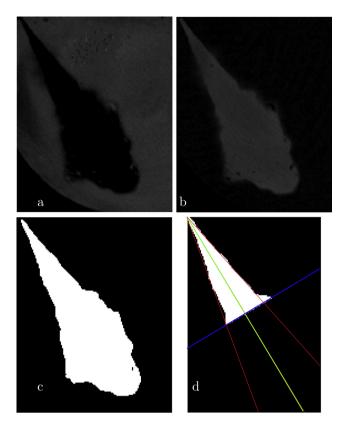
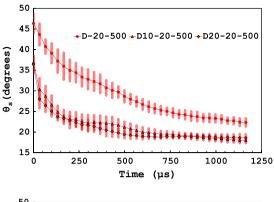


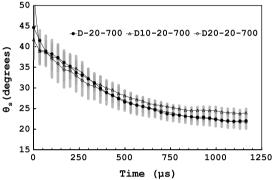
Fig. 2. Shadowgraph Diesel spray image at $t = 1064 \,\mu\text{s}$ (thirty third frame containing spray). (a) Raw image, (b) complement image, (c) black and white image, (d) cropped, processed measurement image.

 $(P_{amb}$ = 30 bar). Both figures include error bars the size of one standard deviation (σ) from the mean. The interval between each time step was 33.25 μs (camera frame rate). The plots have been constructed with the injection delay period removed. The end of injection (EOI) was not well defined so a cut-off at frame 55 $(t=1829~\mu s$ after SOI) was used for all cases.

The injections started with a θ_S between 36° and 52°. As the injection continues, θ_S decreases and appears to approach (quasi) constant values of between 18° and 24°, after approximately 1000 µs. The standard deviation associated with the 15 injections used to determine the mean value decreases as the injection progresses, as evidenced by the reduction in the size of the error bars for each condition. This is also an indication that the spray angle value is reaching a quasi-steady, less transient value and the spray is forming a less transient spray structure. Measurement uncertainties were considered and have been determined to arise from the image collection system. Sources of the uncertainty include varying intensity of the LED, window fouling, optical misalignment, lens fouling and camera response. Whilst the magnitude of these uncertainties may not be determined, the measurement uncertainty has been handled by the standard deviation of each data set, evidence by error bars in Figs. 3 and 4.

Figs. 3 and 4 show that varying the injection pressure had little effect on θ_S for the Diesel fuel sprays. This is in accordance with previous works [20–22,50–52] which found the spray angle for complete atomized sprays to be independent of injection pressure and only dependent on the gas density. For D10 and D20 sprays at P_{inj} = 500 bar, there was a distinct reduction in θ_S compared to their sprays at P_{inj} = 700 and 1000 bar. The difference between the D10, D20 and the neat Diesel fuel spray angle at P_{inj} = 500 bar are not so pronounced at the higher ambient density. This is evidenced by the larger standard deviation of the angles at the higher density, with





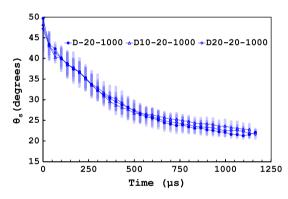


Fig. 3. Fuel injection spray angle variation with time with Diesel fuel (circle), D10 (triangle) and D20 (diamond) and ambient gas density $\rho_a = 22.6 \text{ kg/m}^3$ $P_{amb} = 20 \text{ bar}$, 500 bar are shown in red, 700 bar in black and 1000 bar in blue line. Error bars are the size of one standard deviation for the 15 injections used to calculate the mean. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

considerable overlap of the error bars. It is evident that the emulsification process had an impact on the fuel spray angle at the injection pressure of 500 bar. The difference in θ_S between the two emulsions was small at this injection pressure. The emulsification process appears to have reduced θ_S when compared with the neat Diesel sprays (at P_{inj} = 500 bar) by between 3° and 4.5° approximately.

Figs. 3 and 4 show that for all injection pressures, an increase in ρ_a lead to an increase in the θ_S for the neat Diesel fuel sprays but not for the emulsified fuel sprays. This is shown a little more clearly in Fig. 5 which shows the average, quasi-steady spray angle (θ_{Sav}) from the arithmetic mean of the final 5 θ_S values (time after SOI = 1097 μ s to 1230 μ s) for each condition. This value is used as a representative value of the spray cone angle for each condition. In Fig. 5 the measured θ_{Sav} for the neat Diesel fuel are of a similar value for each injection pressure at the same ambient density. As the ambient density was increased, θ_{Sav} shown a small increase. For the D10, the θ_{Sav} of the 500 bar injection at each ambient

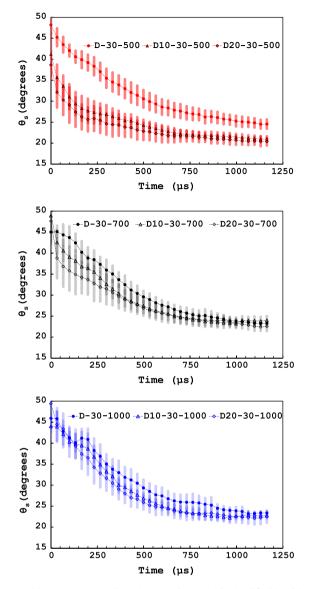


Fig. 4. Fuel injection spray angle variation with time with Diesel fuel (circle), D10 (triangle) and D20 (diamond) and ambient gas density $\rho_a = 34.5 \text{ kg/m}^3$ $P_{amb} = 30 \text{ bar}$. 500 bar are shown in red, 700 bar in black and 1000 bar in blue line. Error bars are the size of one standard deviation for the 15 injections used to calculate the mean. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

density was much lower than for the 700 and 1000 bar injections. The small increase in the θ_{Sav} with the increase in ambient density was not observed for the 700 and 1000 bar injections. This trend is repeated for the D20 fuel sprays.

The spray angle is known to be a function of the ratio of the ambient (gas) density and fuel (liquid) density (ρ_a/ρ_f). Compared with previous works, the range of the density ratios in this study was limited, with only two chamber pressures being used, 20 bar and 30 bar; resulting in two ambient densities of 22.6 kg/m³ and 34.5 kg/m³ respectively. The emulsification process resulted in a change of the fuel density as well. The fuel densities were measured to be 814 kg/m³, 829 kg/m³ and 876 kg/m³ for D, D10 and D20 respectively (Table 2). The resultant density ratio range is 0.026–0.042, which is lower than that of a modern, turbocharged common rail CI engine. Fig. 6 shows the variation of the average, quasi-steady spray angle (θ_{Sav}) with the density ratio ρ_a/ρ_f for Diesel fuel, D10 and D20 sprays. For each of the plots

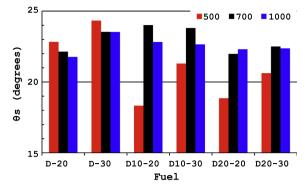


Fig. 5. Representative spray cone angle value taken from the quasi-steady, near constant period at the EOI for Diesel fuel, D10, D20 at each condition. All 500 bar injections are in red, 700 bar in black and 1000 in blue. -20 are injections are with $\rho_a=22.6\,{\rm kg/m^3}$ P_{amb} = 20 bar, -30 are injections with $\rho_a=34.5\,{\rm kg/m^3}$ P_{amb} = 30 bar. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

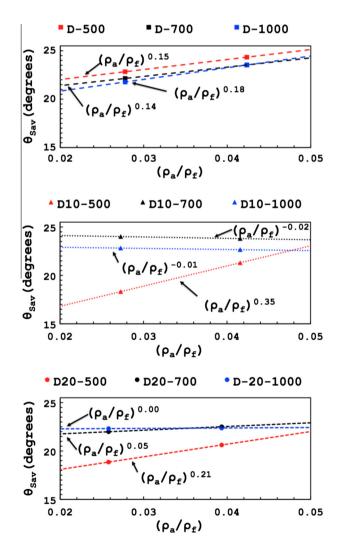


Fig. 6. Variation of the θ_{Sav} of Diesel fuel spray with ρ_a/ρ_f . P_{inj} = 500 (red), 700 (black) and 1000 bar (blue). Trend line has been fitted to the points for each injection pressure with the exponent shown. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

the red broken line is fitted to the 500 bar injection, the black broken line to the 700 bar injections and the blue broken line to the 1000 bar injections. The exponent of the density ratio (a where

 $\theta \propto (\rho_a/\rho_f)^a$) for each injection pressure and fuel was determined using logarithms. For the neat Diesel fuel sprays, each injection pressure shows a similar trend, with the exponent of the density ratio for each pressure very similar, $(\rho_a/\rho_f)^{0.14-0.18}$. These values are in accordance with previous findings for Diesel fuel sprays. The injection pressure had little, to no effect and the increase in density ratio resulted in an increase of the spray cone angle. For D10 and D20, the 500 bar injections had a much smaller spray angle at the lower ambient density than for the 700 and 1000 bar injections. The spray angle of the 500 bar injections did increase with the increasing density ratio, with a = 0.35 and 0.21 for D10 and D20 respectively. The angle for the 500 bar injections for both emulsified fuels was smaller than it's neat Diesel counterpart.

The increase in spray angle with density ratio is not observed for the two emulsified fuels at the injection pressures of 700 and 1000 bar. This is demonstrated by the small value of *a* for these conditions; -0.02 (700 bar, D10 injections) to 0.05 (700 bar, D20 injections). Fig. 6 supports the statement that the emulsified fuels, at 700 and 1000 bar injection pressure, shown no change in the spray angle with changing ambient density.

The values of a have been determined using two data points. The findings are not being overstated or stated outside of the measurement range of the experimentation conducted here, the limitations of the findings are accepted. The values determined for the neat Diesel fuel are reasonable when compared with previous findings so it is fair to say that the values should also be realistic for the emulsified fuels. The value of a determined is being used as an indicator of any effects the emulsification had at these conditions and not as a fundamental finding of the sprays. The value a for the D10 and D20, 500 bar injections suggests that at P_{ini} = 500 bar, the emulsification results in the ambient density increase having a larger effect on the spray cone angle compared with neat Diesel, but the actual value of the spray angle is reduced relative to the neat Diesel sprays at these conditioned. The emulsification suppressed the effect of the ambient density increase for the 700 bar and 1000 bar injection pressures.

3.2. Tip penetration

Figs. 7 and 8 show the temporal evolution of the spray tip penetration for Diesel fuel, D10 and D20 sprays at each injection pres-

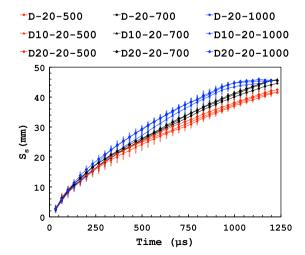


Fig. 7. Fuel injection spray tip penetration variation with time after SOI for Diesel fuel, D10 and D20. P_{inj} = 500, 700 and 1000 bar. ρ_a = 22.6 kg/m³ (P_{amb} = 20 bar). Error bars of one standard deviation. Determined using the shadowgraph image sequences.

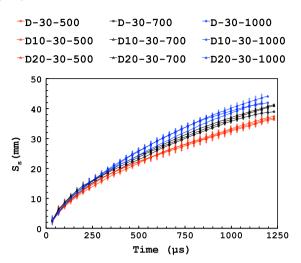


Fig. 8. Fuel injection spray tip penetration variation with time after SOI for Diesel fuel, D10 and D20. P_{inj} = 500, 700 and 1000 bar. ρ_a = 34.5 kg/m³ (P_{amb} = 30 bar). Error bars of one standard deviation. Determined using the shadowgraph image sequences.

sure with ambient density of 22.6 kg/m³ and 34.5 kg/m³ respectively. The mean value shown is determined from 15 injections. As with the spray cone angle values, the injection delay period has been removed. The first appearance of spray has not been set at t = 0 as this would lead to a physically impossible situation where the spray started before t = 0. The tip penetration has not been back extrapolated to 0 mm at t = 0 as this relies on the assumption that the initial rate of penetration (velocity) during the very early period of the spray evolution was linear with time. Due to the varying injection delay between each condition and the temporal resolution only being as high as the camera frame rate (33.25 µs), a linear correction was applied to align the penetration profiles so all profiles have a common origin. The common origin was set at $t = 33.25 \,\mu s$ with each tip measurement made at 33.25 µs intervals (frame rate of the camera). The linear correction allows a fair comparison between each case to be made and observe the change in tip penetration for each time step. Both figures include error bars the size of one standard deviation (σ) from the mean for the 15 injections used to calculate the mean S_s . The standard deviation from the mean was included to show the good repeatability between each injection event and the statistical significant of the mean S_S determined. Figs. 7 and 8 demonstrate that emulsification seemed to have had little to no effect on the temporal evolution of the spray tip penetration when compared with the neat Diesel spray results.

As has been noted in previous works [17,18,28,29], increasing the injection pressure lead to an increase in rate of the spray tip penetration while an increase in the ambient density lead to a reduction in the rate of the spray tip penetration. An increase in P_{inj} results in an increase in the spray momentum and an increase in ρ_{amb} results in an increase in aerodynamic drag on the emerging spray.

An example of the methodology of the tip penetration analysis influenced by the Hiroyasu and Arai model is to examine the temporal tip penetration using a log plot. Experimental data points are plotted on a logarithmic plot as in Figs. 9 and 10 and were used to create average trend lines.

As described by Hiroyasu and Arai [20] and in subsequent works [13,17,21,53] the plots describe two distinct periods of spray tip temporal evolution. The slope of the initial period of the curve is usually described as being equal to 1. The slope of the initial period of the curve in Figs. 9 and 10 is 1.12 and 1.03 respectively which is in reasonable agreement. During this period the rate of spray tip

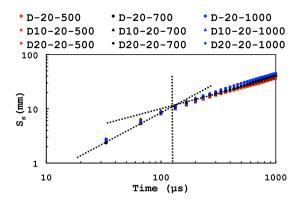


Fig. 9. Log-penetration with log-time plot for Diesel fuel, D10 and D20 spray tip penetration. P_{inj} = 500, 700 and 1000 bar. ρ_a = 22.6 kg/m³ (P_{amb} = 20 bar). Determined using the shadowgraph image sequences. Linear trend line fitted to the two portions of the tip penetration with intersection at break-up time.

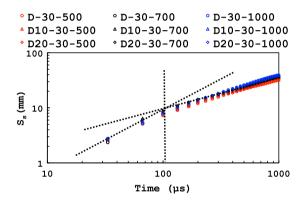


Fig. 10. Log-penetration with log-time plot for Diesel fuel, D10 and D20 spray tip penetration. P_{inj} = 500, 700 and 1000 bar. ρ_a = 34.5 kg/m³ (P_{amb} = 30 bar). Determined using the shadowgraph image sequences. Linear trend line fitted to the two portions of the tip penetration with intersection at break-up time.

penetration was nearly linear with time, $S \propto t$, and is thought to be dominated by the propagation of the liquid core into the surrounding atmosphere [25]. The tip velocity is thought to be determined by the fuel injection velocity because the momentum exchanged between the spray and the surrounding ambient atmosphere is not significant during the very early period [15].

After a short time the slope changes and is most often approximated to a value of 0.5 ($S \propto t^{0.5}$). The slope of the curve in this second period in Figs. 9 and 10 is 0.6. This transition is often described as the spray break-up time and is defined as the time where the fuel spray starts to exchange momentum with the surrounding atmosphere and the tip velocity is reduced, this may be referred to as aerodynamic drag in some cases. It is also suggested this transition time is the instance when spray mixture changes from being dominated by injected liquid to being dominated by entrained gas [21,53]. The vertical broken line in Figs. 9 and 10 shows the average transition time for the ρ_a = 22.6 and kg/m³ ρ_a = 34.5 kg/m³ conditions. The times have been extracted and are shown in Table 3. As the ambient density is increased the transition time after the SOI becomes shorter. The increase in the ambient density has lead to a reduction in the break-up time due to increasing aerodynamic drag and momentum exchange with the ambient gas.

Table 3 Spray tip penetration transition times.

Ambient density (kg/m³)	g/m³) Transition time (μs ASOI)	
22.6	132	
34.5	108	

As discussed in the introduction, adherence to the linear relationship during the pre-break-up period is clearly a physical impossibility. In the very instance of needle opening the fuel will be accelerating from 0 ms⁻¹ to an injection velocity observed here of approximately 70–100⁻¹, the rate of change of penetration during this early period cannot be linear. The few data points available at this period make any extrapolation back to the origin susceptible to misinterpretation and should be avoided, as exemplified in the work [15].

Figs. 11–13 show the temporal evolution of the spray tip penetration for Diesel fuel at injection pressures of 500, 700 and 1000 bar respectively, ambient density is ρ_a = 22.6 kg/m³ and compares them to the models and data fits discussed in the introduction.

It is evident that the Hiroyasu model overestimates in all cases compared to the measured S_S , with an earlier transition time. At the lower injection pressure, the Kostas fit underestimates but as injection pressure increases it overestimates the tip penetration. A similar trend is observed with the Taskiran fit which uses a modified Hiroyasu model for the period after beak-up. It is this portion of the model which most closely matches the measured S_S in the later stages of the injection. It is interesting that this modified Hiroyasu used by Taskiran is the first time that the nozzle geometry, in terms of conicity, is taken into account. Even with this, the measured data is a long way from that predicted in the various models, however, the difference between the models themselves shows the variability that is present in the literature concerning the temporal evolution of spray tip, both experimentally collected and modeled/data fitted.

The results presented pertaining to the spray cone angle and tip penetration of the emulsions has not been identified in previous emulsion spray works where these conditions and parameters have not been considered. The non-reactive, cold conditions of the ambient environment and the range of injection pressures used have no comparison in the literature [30–32].

3.3. Summary and conclusion

Sequences of consecutive images of Diesel fuel, D10 and D20 injection sprays were collected using a shadowgraph system at a frame rate of 30,075 fps. A research LED system was designed and built to provide illumination as an alternative to a laser system. Image sequences were used to determine the temporal evolution of the spray cone angle and the spray tip penetration for the fuel sprays. Three injection pressures, 500, 700 and 1000 bar were considered. Injections took place into nitrogen at an ambient tem-

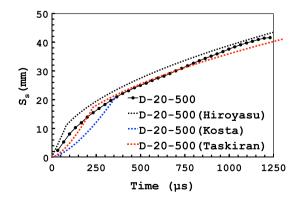


Fig. 11. Fuel injection spray tip penetration variation with time after SOI for Diesel fuel. P_{inj} = 500. ρ_a = 22.6 kg/m³. Experimental in black, Hiyoyasu model (broken black), Kosta model (blue) and Taskiran model (red) for same condition. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

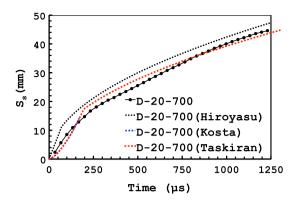


Fig. 12. Fuel injection spray tip penetration variation with time after SOI for Diesel fuel. P_{inj} = 700. ρ_a = 22.6 kg/m³. Experimental in black, Hiyoyasu model (broken black), Kosta model (blue) and Taskiran model (red) for same condition. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

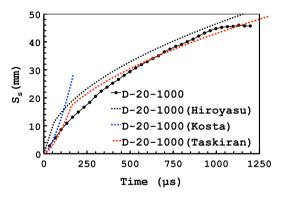


Fig. 13. Fuel injection spray tip penetration variation with time after SOI for Diesel fuel. P_{inj} = 1000. ρ_a = 22.6 kg/m³. Experimental in black, Hiyoyasu model (broken black), Kosta model (blue) and Taskiran model (red) for same condition. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

perature of $20\,^{\circ}\text{C}$ with two ambient densities of $22.6\,\text{kg/m}^3$ and $34.5\,\text{kg/m}^3$ ($20\,\text{and}\,30\,\text{bar}$ ambient pressure respectively). For each injection condition, a total of $15\,\text{injections}$ was used to determine the mean spray angle and tip penetration. The following are primary observations made during the study:

- \bullet For all conditions the measured angle started at between 36° and 52°. As the injections progressed, the angle gradually decreased until around 1000 μ s after the SOI when the angle appeared to approach a quasi-steady value of between 18° and 24° for all conditions.
- The standard deviation of the mean spray angle, from the 15 injections used, reduced in value as the injections progressed, suggesting the spray formed a more stable less transient angle as injection progressed.
- The final five measurements were used to extract representative values of the spray angle for each condition for comparison purposes.
- The injection pressure had no discernible influence on the spray angle for the Diesel fuel sprays. For the D10 and D20 fuels, the spray angles for the 500 bar injections were considerably smaller than the spray angles for the 700 and 1000 bar injections.
- Increasing the ambient density resulted in a larger spray angle for the Diesel fuel sprays. For the D10 and D20 sprays, the increase in ambient density resulted in an increase in the spray angle for the 500 bar injections but not for the 700 and 1000 bar injections.

• With an injection pressure of 500 bar, both emulsions had a smaller spray angle than Diesel fuel at the same conditions.

From the results, the following conclusions were reached:

- Emulsification of the fuel lead to a reduction in the spray angle when the injection pressure was 500 bar.
- Emulsification of the fuel reduced the influence of the ambient gas density upon the spray angle when the injection pressure was 700 and 1000 bar.
- Measurements made at this temporal resolution support the previous models suggesting a linear dependence with time during the initial period, $S \propto t$ with a transition time after the SOI when the dependence changes to $S \propto t^{0.5}$.
- Previous models either under or overestimate tip penetration when compared with the measurements made in this work.
- The LED system used offers a cheap, reliable alternative illumination source for high speed imaging work.

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