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Discrete exact solutions to some nonlinear differential-difference equations via the (G'/G)-expansion method

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ABSTRACT

We extended the (G'/G)-expansion method to two well-known nonlinear differential-difference equations, the discrete nonlinear Schrödinger equation and the Toda lattice equation, for constructing traveling wave solutions. Discrete soliton and periodic wave solutions with more arbitrary parameters, as well as discrete rational wave solutions, are revealed. It seems that the utilized method can provide highly accurate discrete exact solutions to NDDEs arising in applied mathematical and physical sciences.

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1. Introduction

The study of nonlinear differential-difference equations (NDDEs) has attracted a wide interest since the original work of Fermi et al. in the 1950s [1]. NDDEs, treated as models of some physical phenomena, have become the focus of common concern and played a crucial role in various branches of applied sciences such as biophysics, condensed matter physics and mechanical engineering, and in different physical problems such as atomic chains, currents in electrical networks and molecular crystals [2–5]. We can also encounter NDDEs in numerical simulation of soliton dynamics in high energy physics. Paying more attention to such equations, many integrable NDDEs have been proposed by the researchers, such as the Toda lattice equation [6], the Volterra lattice equation [7], the discrete KdV equation [8] and the Ablowitz–Ladik lattice equation [9]. Contrary to difference equations being fully discrete, NDDEs are semi-discrete with some (or all) of their space variables discrete while time is usually continuous.

The investigation of discrete exact analytic solutions of NDDEs plays an important role in the study of their corresponding nonlinear physical phenomena. Many effective analytic methods for solving nonlinear evolution equations (NEEs) are available in the literature [10–23]. How to extend newly developed methods for NEEs to solve NDDEs is an interesting and important issue. To mention some of the research made on this direction, Hu and Ma [24] used Hirota's bilinear method to construct special soliton-like solutions of the Toeplitz lattice. With the development of computer algebra systems, Baldwin and his co-workers [25] devised an algorithm for discrete nonlinear models in terms of a tanh function. Their work can be thought as a breakthrough for solving NDDEs symbolically. By applying the Jacobi elliptic function expansion method, explicit and exact traveling wave solutions to three NDDEs are found by Liu et al. [26]. An extended Jacobian elliptic function algorithm is presented by Dai et al. [27]. Xie et al. [28] studied the discrete sine-Gordon equation implementing a method based on the Riccati equation expansion. Zhu [29,30] extended the Exp-function method to NDDEs to obtain physically important solutions. Yang et al. [31] considered two nonlinear lattice equations using the so-called ADM-Padé technique. The homotopy perturbation method is applied by Zhu et al. [32] to a nonlinear differential-difference equation arising in nanotechnology. Zhen [33] developed a discrete tanh method. Lately, Aslan [34] presented a generalization of the extended simplest equation method to NDDEs, and so on.

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Whilst there has been considerable work done on finding exact solutions to NEEs, little work is being done to symbolically compute exact discrete solutions of NDDEs as far as we could verify. Not long ago, Wang et al. [35] proposed the (G'/G)-expansion method to obtain exact solutions of NEEs arising in mathematical physics. Based on Wang et al.'s pioneer work and his followers, the (G'/G)-expansion method has become popular in the research community, and there has been a number of studies refining the initial idea [36–50]. The method is efficient, reliable and faster by means of a symbolic computation system. It is also powerful for taking full advantage of linear theory of ordinary differential equations.

It is hard to extend an analytic method for NDDEs because of the difficulty which usually arises when we search for iterative relations from indices n to $n \pm i$. Fortunately, Zhang et al. [51] have successfully extended the (G'/G)-expansion method to the (2 + 1)-dimensional TLE and the discrete Wadati equation. Our objective in this study is to further extend the (G'/G)-expansion method to two physically important NDDEs for the first time. We slightly adjust the proposed algorithm in [51] by considering a third case for the inclusion of rational solutions as well.

The rest of this paper is organized as follows: in Section 2, we describe the (G'/G)-expansion method for finding exact discrete traveling wave solutions of NDDEs, and state the main steps. In Section 3, we illustrate our procedure in detail with the discrete nonlinear Schrödinger equation (DNSE) and the Toda lattice equation (TLE). Finally, some conclusions are given in Section 4.

2. The (G'/G)-expansion method for NDDEs

Let us consider a system of M polynomial NDDEs in the form

$$P\mathbf{u}_{n+p_1}(\mathbf{x}), \dots, \mathbf{u}_{n+p_k}(\mathbf{x}), \dots, \mathbf{u}'_{n+p_1}(\mathbf{x}), \dots, \mathbf{u}'_{n+p_k}(\mathbf{x}), \dots, \mathbf{u}'^{(r)}_{n+p_1}(\mathbf{x}), \dots, \mathbf{u}^{(r)}_{n+p_k}(\mathbf{x}) = 0,$$
 (1)

where the dependent variable $\mathbf{u_n}$ have M components $u_{i,\mathbf{n}}$ and so do its shifts, the continuous variable \mathbf{x} has N components x_i , the discrete variable \mathbf{n} has Q components n_j , the k shift vectors $\mathbf{p}_i \in \mathbb{Z}^Q$, and $\mathbf{u}^{(r)}(\mathbf{x})$ denotes the collection of mixed derivative terms of order r. We summarize our five step-algorithm as follows:

Step 1: For finding traveling wave solutions to Eq. (1), we introduce the wave transformation

$$\mathbf{u}_{\mathbf{n}+\mathbf{p}_{s}}(\mathbf{x}) = \mathbf{U}_{\mathbf{n}+\mathbf{p}_{s}}(\xi_{\mathbf{n}}), \quad \xi_{\mathbf{n}} = \sum_{i=1}^{Q} d_{i} n_{i} + \sum_{j=1}^{N} c_{j} x_{j} + \zeta, \quad (s = 1, 2, \dots, k),$$
(2)

where the coefficients $c_1, c_2, \ldots, c_N, d_1, d_2, \ldots, d_O$ and the phase ζ are all constants. Then, Eq. (1) takes the form

$$P\textbf{U}_{n+p_{1}}(\xi_{n}),\ldots,\textbf{U}_{n+p_{k}}(\xi_{n}),\ldots,\textbf{U}_{n+p_{1}}'(\xi_{n}),\ldots,\textbf{U}_{n+p_{k}}(\xi_{n}),\ldots,\textbf{U}_{n+p_{k}}^{(r)}(\xi_{n}),\ldots,\textbf{U}_{n+p_{k}}^{(r)}(\xi_{n})=0. \tag{3}$$

Step 2: We assume that the solution of Eq. (3) can be expressed in the finite series expansion

$$\mathbf{U}_{\mathbf{n}}(\xi_{\mathbf{n}}) = \sum_{l=0}^{m} \boldsymbol{a}_{l} \left(\frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} \right)^{l}, \quad \boldsymbol{a}_{m} \neq 0, \tag{4}$$

where m (a positive integer) and a_l 's are constants to be determined later, $G(\xi_n)$ is the general solution of the auxiliary equation

$$G''(\xi_n) + \lambda G'(\xi_n) + \mu G(\xi_n) = 0 \tag{5}$$

in which λ and μ are constants to be specified later and prime denotes derivative with respect to ξ_n . The general solution of Eq. (5) is well-known for us, and hence we get the following cases:

$$\frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} = \frac{\sqrt{\lambda^2 - 4\mu}}{2} \left(\frac{C_1 \cosh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\xi_{\mathbf{n}}\right) + C_2 \sinh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\xi_{\mathbf{n}}\right)}{C_1 \sinh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\xi_{\mathbf{n}}\right) + C_2 \cosh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\xi_{\mathbf{n}}\right)} \right) - \frac{\lambda}{2}, \quad \lambda^2 - 4\mu > 0, \tag{6a}$$

$$\frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} = \frac{\sqrt{4\mu - \lambda^2}}{2} \left(\frac{-C_1 \sin\left(\frac{\sqrt{4\mu - \lambda^2}}{2} \xi_{\mathbf{n}}\right) + C_2 \cos\left(\frac{\sqrt{4\mu - \lambda^2}}{2} \xi_{\mathbf{n}}\right)}{C_1 \cos\left(\frac{\sqrt{4\mu - \lambda^2}}{2} \xi_{\mathbf{n}}\right) + C_2 \sin\left(\frac{\sqrt{4\mu - \lambda^2}}{2} \xi_{\mathbf{n}}\right)} \right) - \frac{\lambda}{2}, \quad \lambda^2 - 4\mu < 0, \tag{6b}$$

$$\frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} = \frac{C_1}{C_1 \xi_{\mathbf{n}} + C_2} - \frac{\lambda}{2}, \quad \lambda^2 - 4\mu = 0, \tag{6c}$$

where C_1 and C_2 are arbitrary constants.

Step 3: A simple calculation leads to the identity

$$\xi_{n+n} = \xi_n + \varphi_{\epsilon}, \quad \varphi_{\epsilon} = p_{\epsilon_1} d_1 + p_{\epsilon_2} d_2 + \dots + p_{\epsilon_N} d_0,$$
 (7)

where p_{sj} is the jth component of the shift vector \mathbf{p}_s . Thus, using the trigonometric/hyperbolic function identities and considering the functions (6a–c) as well as (7), we derive uniform formulas

$$\mathbf{U_{n+p_s}}(\xi_{\mathbf{n}}) = \sum_{l=0}^{m} a_l \left(\frac{\frac{\lambda}{2} + \frac{C'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} + \frac{\sqrt{\lambda^2 - 4\mu}}{2} \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\varphi_s\right)}{1 + \frac{2}{\sqrt{\lambda^2 - 4\mu}}\left(\frac{\lambda}{2} + \frac{C'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})}\right) \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\varphi_s\right)} - \frac{\lambda}{2} \right)^l, \quad a_m \neq 0, \quad \lambda^2 - 4\mu > 0,$$

$$(8a)$$

$$\mathbf{U_{n+p_s}}(\xi_{\mathbf{n}}) = \sum_{l=0}^{m} a_l \left(\frac{\frac{\lambda}{2} + \frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} - \frac{\sqrt{4\mu - \lambda^2}}{2} \tan\left(\frac{\sqrt{4\mu - \lambda^2}}{2}\varphi_s\right)}{1 + \frac{2}{\sqrt{4\mu - \lambda^2}} \left(\frac{\lambda}{2} + \frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})}\right) \tan\left(\frac{\sqrt{4\mu - \lambda^2}}{2}\varphi_s\right)} - \frac{\lambda}{2} \right)^l, \quad a_m \neq 0, \quad \lambda^2 - 4\mu < 0,$$

$$(8b)$$

$$\mathbf{U}_{\mathbf{n}+\mathbf{p}_{s}}(\xi_{\mathbf{n}}) = \sum_{l=0}^{m} a_{l} \left(\left(\left(\frac{\lambda}{2} + \frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} \right) \middle/ \left(1 + \left(\frac{\lambda}{2} + \frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} \right) \varphi_{s} \right) \right) - \frac{\lambda}{2} \right)^{l}, \quad a_{m} \neq 0, \quad \lambda^{2} - 4\mu = 0.$$
 (8c)

- Step 4: From Eq. (3), we can easily determine the degree m of Eqs. (4) and (8a-c) by balancing the highest order nonlinear term(s) and the highest-order derivative term in $\mathbf{U_n}(\xi_n)$ as in the continuous case. The leading terms of $\mathbf{U_{n+p_s}}(\mathbf{p_s}\neq 0)$ will not effect the balance since $\mathbf{U_{n+p_s}}$ can be interpreted as being of degree zero in $(G'(\xi_n)/G(\xi_n))$.
- Step 5: Substituting the ansatze (4) and (8a-c) along with (5) into Eq. (3), then setting the coefficients of $(G'(\xi_{\mathbf{n}})/G(\xi_{\mathbf{n}}))^l(l=0,1,2,\ldots)$ to zero, we obtain a system of nonlinear algebraic equations from which the undetermined constants a_l,d_i,c_j,λ and μ can be explicitly found. Finally, we substitute these values into expression (4) and find traveling wave solutions to Eq. (1).

3. Applications

We illustrate the effectiveness and the advantages of our method by giving two examples.

3.1. The discrete nonlinear Schrödinger equation

An important model for discrete solitons is the integrable DNSE [9,52]

$$i\frac{du_n(t)}{dt} = (u_{n+1}(t) - 2u_n(t) + u_{n-1}(t)) - |u_n(t)|^2 (u_{n+1}(t) + u_{n-1}(t)), \tag{9}$$

where $u_n(t) = u(n,t)$ is the displacement of the nth particle from the equilibrium position. Eq. (9) was established by using the inverse scattering method [53], and has many interesting rich mathematical properties and physical applications including dynamics of an harmonic lattice [54], self-trapping on a dimer [4], and pulse dynamics in nonlinear optics [55]. The authors [56–59] successfully studied Eq. (9) by using the Exp-function and the Jacobian elliptic function expansion methods. For solving the DNSE (9), we first make the traveling wave transformation

$$u_n = e^{i\theta_n} \phi_n(\xi_n), \quad \theta_n = d_1 n + c_1 t + \zeta_1, \quad \xi_n = d_2 n + c_2 t + \zeta_2$$
 (10)

and

$$u_{n+1} = e^{i\theta_n} e^{id_1} \phi_{n+1}(\xi_n), \quad u_{n-1} = e^{i\theta_n} e^{-id_1} \phi_{n-1}(\xi_n), \tag{11}$$

where d_1 and c_1 are the wave number of the carrier wave and the frequency, c_2 and d_2 are related to the group velocity and the pulse width, ζ_1 and ζ_2 denote the initial phases. Now, using the Euler formula $e^{\pm id_1} = \cos d_1 \pm i \sin d_1$, Eq. (9) turns into the system

$$\begin{cases} c_1 \phi_n + \cos(d_1) \left(1 - \phi_n^2 \right) (\phi_{n+1} + \phi_{n-1}) - 2\phi_n = 0, \\ c_2 \phi_n' - \sin(d_1) \left(1 - \phi_n^2 \right) (\phi_{n+1} - \phi_{n-1}) = 0. \end{cases}$$
(12)

We expand the solution of (12) in the form of (4). Balancing the linear term of the highest order with the highest nonlinear term in (12) leads to m = 1. Thus, we consider the ansatz

$$\phi_n(\xi_n) = a_0 + a_1 \left(\frac{G'(\xi_n)}{G(\xi_n)} \right), \quad a_1 \neq 0, \tag{13}$$

for the traveling wave solutions of (12). Now, a case analysis follows:

Case 1: When $\lambda^2 - 4\mu > 0$, from (8a), we have

$$\phi_{n\pm 1}(\xi_n) = a_0 + a_1 \left(\frac{\frac{\lambda}{2} + \frac{G'(\xi_n)}{G(\xi_n)} \pm \frac{\sqrt{\lambda^2 - 4\mu}}{2} \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} d_2\right)}{1 \pm \frac{2}{\sqrt{\lambda^2 - 4\mu}} \left(\frac{\lambda}{2} + \frac{G'(\xi_n)}{G(\xi_n)}\right) \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} d_2\right)} - \frac{\lambda}{2} \right), \tag{14}$$

where the signs (\pm) or (\mp) are ordered vertically from now on. Substituting (13) and (14) along with (5) into (12), clearing the denominator and setting the coefficients of all powers like $(G'(\xi_{\mathbf{n}})/G(\xi_{\mathbf{n}}))^i(0 \le i \le 4)$ to zero, we derive a system of nonlinear algebraic equations for $a_0, a_1, c_1, c_2, d_1, d_2, \lambda$, and μ . Solving the set of algebraic equations (we omit to display them for brevity) simultaneously, we get the solution set

$$\begin{cases}
c_{1} = 2 - 2\cos(d_{1})\sec h^{2}\left(\frac{\sqrt{\lambda^{2}-4\mu}}{2}d_{2}\right), & c_{2} = \frac{4\sin(d_{1})}{\sqrt{\lambda^{2}-4\mu}}\tanh\left(\frac{\sqrt{\lambda^{2}-4\mu}}{2}d_{2}\right) \\
a_{0} = \mp \frac{\lambda}{\sqrt{\lambda^{2}-4\mu}}\tanh\left(\frac{\sqrt{\lambda^{2}-4\mu}}{2}d_{2}\right), & a_{1} = \mp \frac{2}{\sqrt{\lambda^{2}-4\mu}}\tanh\left(\frac{\sqrt{\lambda^{2}-4\mu}}{2}d_{2}\right)
\end{cases}, (15)$$

where d_1 and d_2 are arbitrary constants. Hence, from (6a), (10), (13), (14) and (15), we obtain discrete hyperbolic function traveling wave solutions to Eq. (9) as

$$u_{n,1}^{\mp}(t) = \mp \tanh\left(\frac{\sqrt{\lambda^{2} - 4\mu}}{2}d_{2}\right) \left(\frac{C_{1}\cosh\left(\frac{\sqrt{\lambda^{2} - 4\mu}}{2}\xi_{n}\right) + C_{2}\sinh\left(\frac{\sqrt{\lambda^{2} - 4\mu}}{2}\xi_{n}\right)}{C_{1}\sinh\left(\frac{\sqrt{\lambda^{2} - 4\mu}}{2}\xi_{n}\right) + C_{2}\cosh\left(\frac{\sqrt{\lambda^{2} - 4\mu}}{2}\xi_{n}\right)}\right) \times \exp\left(i\left(d_{1}n + \left(2 - 2\cos(d_{1})\sec h^{2}\left(\frac{\sqrt{\lambda^{2} - 4\mu}}{2}d_{2}\right)\right)t + \zeta_{1}\right)\right),$$

$$(16)$$

where $\xi_n=d_2n+rac{4\sin(d_1)}{\sqrt{\lambda^2-4\mu}} anh\left(rac{\sqrt{\lambda^2-4\mu}}{2}d_2
ight)t+\zeta_2,C_1$ and C_2 are arbitrary constants.

Remark 1. As a particular example, if we take $C_2 \neq 0$, $C_1^2 < C_2^2$ in (16) then we get discrete solitary wave solutions to Eq. (9) as

$$u_{n,2}^{\mp}(t) = \mp \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}d_2\right) \tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}\left(d_2n + \frac{4\sin(d_1)}{\sqrt{\lambda^2 - 4\mu}}\tanh\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}d_2\right)t + \zeta_2\right) + \tanh^{-1}\left(\frac{C_1}{C_2}\right)\right) \times \exp\left(i\left(d_1n + \left(2 - 2\cos(d_1)\sec h^2\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}d_2\right)\right)t + \zeta_1\right)\right). \tag{17}$$

Besides, if we set $d_2 = 2k/\sqrt{\lambda^2 - 4\mu}$, $d_1 = p$, $\zeta_1 = \delta$, and $\zeta_2 = 2(\zeta - \tanh^{-1}(C_1/C_2)) / \sqrt{\lambda^2 - 4\mu}$ in (17), then we obtain

$$u_{n,3}^{\pm}(t) = \mp \tanh(k) \tanh(kn + 2\sin(p) \tanh(k)t + \zeta) \times \exp(i(pn + (2 - 2\cos(p) \sec h^2(k))t + \delta)), \tag{18}$$

which are the known dark solitary wave solutions found by Dai and Zhang [57] and Dai et al. [58] in which they are expressed as (20) and (34), respectively. However, in our case, we note that (18) is derived from a more general solution (16) in the sense that it contains more arbitrary parameters. Similarly, our solution (16) can be reduced to the solution (45) presented in Huang and Liu [59] by a suitable modification.

Case 2: When $\lambda^2 - 4\mu < 0$, from (8b), we have

$$\phi_{n\pm 1}(\xi_n) = a_0 + a_1 \left(\frac{\frac{\lambda}{2} + \frac{G'(\xi_n)}{G(\xi_n)}}{1 \pm \frac{2}{\sqrt{4\mu - \lambda^2}} \left(\frac{\lambda}{2} + \frac{G'(\xi_n)}{G(\xi_n)} \right) \tan\left(\frac{\sqrt{4\mu - \lambda^2}}{2} d_2 \right)} - \frac{\lambda}{2} \right). \tag{19}$$

Substituting (13) and (19) along with (5) into (12), clearing the denominator and setting the coefficients of all powers like $(G'(\xi_{\mathbf{n}})/G(\xi_{\mathbf{n}}))^i(0 \le i \le 4)$ to zero, we derive a system of nonlinear algebraic equations for $a_0, a_1, c_1, c_2, d_1, d_2, \lambda$, and μ . Solving the set of algebraic equations simultaneously, we get the solution set

$$\begin{cases}
c_{1} = 2 - 2\cos(d_{1})\sec^{2}\left(\frac{\sqrt{4\mu-\lambda^{2}}}{2}d_{2}\right), & c_{2} = \frac{4\sin(d_{1})}{\sqrt{4\mu-\lambda^{2}}}\tan\left(\frac{\sqrt{4\mu-\lambda^{2}}}{2}d_{2}\right) \\
a_{0} = \mp\frac{\lambda}{\sqrt{4\mu-\lambda^{2}}}\tan\left(\frac{\sqrt{4\mu-\lambda^{2}}}{2}d_{2}\right), & a_{1} = \mp\frac{2}{\sqrt{4\mu-\lambda^{2}}}\tan\left(\frac{\sqrt{4\mu-\lambda^{2}}}{2}d_{2}\right)
\end{cases}, (20)$$

where d_1 and d_2 are arbitrary constants. Hence, from (6b), (10), (13), (19) and (20), we obtain discrete trigonometric function traveling wave solutions to Eq. (9) as

$$u_{n,4}^{\mp} = \mp \tan\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}d_{2}\right) \left(\frac{C_{2}\cos\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\zeta_{n}\right) - C_{1}\sin\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\zeta_{n}\right)}{C_{1}\cos\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\zeta_{n}\right) + C_{2}\sin\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\zeta_{n}\right)}\right) \times \exp\left(i\left(d_{1}n + \left(2 - 2\cos(d_{1})\sec^{2}\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}d_{2}\right)\right)t + \zeta_{1}\right)\right), \tag{21}$$

where $\xi_n = d_2 n + \frac{4\sin(d_1)}{\sqrt{4\mu-\lambda^2}}\tan\left(\frac{\sqrt{4\mu-\lambda^2}}{2}d_2\right)t + \zeta_2, C_1$ and C_2 are arbitrary constants.

Remark 2. In particular, if we take $C_2 \neq 0$, $C_1^2 < C_2^2$ in (21) then we get discrete periodic wave solutions to Eq. (9) as

$$u_{n,5}^{\pm} = \mp \tan\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}d_{2}\right) \cot\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\left(d_{2}n + \frac{4\sin(d_{1})}{\sqrt{4\mu - \lambda^{2}}}\tan\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}d_{2}\right)t + \zeta_{2}\right) + \tan^{-1}\left(\frac{C_{1}}{C_{2}}\right)\right) \times \exp\left(i\left(d_{1}n + \left(2 - 2\cos(d_{1})\sec^{2}\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}d_{2}\right)\right)t + \zeta_{1}\right)\right). \tag{22}$$

Moreover, if we set $d_2 = 2k/\sqrt{4\mu - \lambda^2}$, $d_1 = p$, $\zeta_1 = \delta$, and $\zeta_2 = 2(\zeta - \tan^{-1}(C_1/C_2))/\sqrt{4\mu - \lambda^2}$ in (22), then we obtain

$$u_{n,6}^{\mp}(t) = \mp \tan(k)\cot(kn + 2\sin(p)\tan(k)t + \zeta) \times \exp(i(pn + (2 - 2\cos(p)\sec^2(k))t + \delta)), \tag{23}$$

which turns out to be the singular solitonic solutions (45) derived in Dai et al. [58]. Likewise, assigning special values to the parameters in our solution (21), we can get many known solutions, for example, in Dai et al. [57] as well as Huang and Liu [59]. We omit to display them for making the discussion short.

Case 3: When $\lambda^2 - 4\mu = 0$, from (8c), we have

$$\phi_{n\pm 1}(\xi_n) = a_0 + a_1 \left(\left(\left(\frac{\lambda}{2} + \frac{G'(\xi_n)}{G(\xi_n)} \right) \middle/ \left(1 \pm \left(\frac{\lambda}{2} + \frac{G'(\xi_n)}{G(\xi_n)} \right) d_2 \right) \right) - \frac{\lambda}{2} \right). \tag{24}$$

Substituting (13) and (24) along with (5) into (12), clearing the denominator and setting the coefficients of all powers like $(G'(\xi_{\mathbf{n}})/G(\xi_{\mathbf{n}}))^i(0 \le i \le 4)$ to zero, we derive a system of nonlinear algebraic equations for $a_0, a_1, c_1, c_2, d_1, d_2, \lambda$, and μ . Solving the set of algebraic equations simultaneously, we get the solution set

$$\left\{c_1 = 2(1 - \cos(d_1)), \ c_2 = 2d_2\sin(d_1), \ a_0 = \mp \frac{\lambda d_2}{2}, \ a_1 = \mp d_2\right\},\tag{25}$$

where d_1 and d_2 are arbitrary constants. Hence, from (6c), (10), (13), (24) and (25), we obtain discrete rational wave solutions to Eq. (9) as

$$u_{n,7}^{\mp}(t) = \mp \frac{C_1 d_2}{C_1 (d_2 n + 2 d_2 \sin(d_1) t + \zeta_2) + C_2} \times \exp(i (d_1 n + 2(1 - \cos(d_1)) t + \zeta_1)), \tag{26}$$

where C_1 and C_2 are arbitrary constants.

Remark 3. We observe that the rational solutions (26) are presented here for the first time and they do not appear in [57–59].

3.2. The Toda lattice equation

Next, we consider the so-called Toda lattice equation [6,10,60] which reads

$$\frac{d^2 u_n(t)}{dt^2} = \alpha (2e^{-\beta u_n(t)} - e^{-\beta u_{n+1}(t)} - e^{-\beta u_{n-1}(t)}). \tag{27}$$

Since it is difficult to apply the method directly to Eq. (27), we introduce the transformation

$$e^{-\beta u_n(t)} = 1 + \frac{\nu_n(t)}{\alpha},\tag{28}$$

which immediately reduces Eq. (27) into

$$\frac{d^2}{dt^2}\ln\left(1+\frac{\nu_n(t)}{\alpha}\right) = \beta(\nu_{n+1}(t)-2\nu_n(t)+\nu_{n-1}(t)). \tag{29}$$

Assuming $v_n(t) = V_n(\xi_n)$, $\xi_n = d_1 n + c_1 t + \zeta$ in Eq. (29), we get

$$c_1^2 \frac{d^2}{d\xi_n^2} ln \left(1 + \frac{V_n(\xi_n)}{\alpha} \right) = \beta(V_{n+1}(\xi_n) - 2V_n(\xi_n) + V_{n-1}(\xi_n)). \tag{30}$$

Since the procedure is the same as in the previous section, we will omit most of the details here. Now, by the homogeneous balance principle, we can assume the ansatz

$$V_n(\xi_{\mathbf{n}}) = a_0 + a_1 \left(\frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} \right) + a_2 \left(\frac{G'(\xi_{\mathbf{n}})}{G(\xi_{\mathbf{n}})} \right)^2, \quad a_2 \neq 0$$

$$(31)$$

for the traveling wave solutions of Eq. (30). After a careful analysis, we end up with the following cases:

Case 1: $\lambda^2 - 4\mu > 0$.

Substituting (31) along with $V_{n+1}(\xi_n)$ and $V_{n-1}(\xi_n)$ derived from (8a) into Eq. (30), clearing the denominator and equating the coefficients of $(G'(\xi_n)/G(\xi_n))^i$ (0 $\leq i \leq 10$) to zero, and solving the resulting algebraic system for $a_0, a_1, a_2, c_1, d_1, \lambda$, and μ , we get a solution set (denoted in curly brackets from now on) and the corresponding discrete hyperbolic function traveling wave solution to Eq. (27) as follows:

$$\left\{ a_0 = \frac{-(\alpha\beta + c_1^2\mu)}{\beta} + \frac{c_1^2(\lambda^2 - 4\mu)}{4\beta} \operatorname{csch}^2\left(\frac{\sqrt{\lambda^2 - 4\mu}}{2}d_1\right), \quad a_1 = -\frac{\lambda c_1^2}{\beta}, \quad a_2 = -\frac{c_1^2}{\beta} \right\},$$
(32)

$$u_{n,1}(t) = -\frac{1}{\beta} \ln \left(\frac{\lambda^2 - 4\mu c_1^2}{4\alpha\beta} \left(\frac{1 + \csc h^2 \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} d_1 \right)}{-\left(\frac{c_1 \cosh \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} \xi_n \right) + c_2 \sinh \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} \xi_n \right)}{c_1 \sinh \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} \xi_n \right) + c_2 \cosh \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} \xi_n \right)} \right)^2 \right) \right),$$
(33)

where $\xi_n = d_1 n + c_1 t + \zeta_1 C_1$ and C_2 are arbitrary constants.

Remark 4. For instance, if we take $C_2 \neq 0$, $C_1^2 < C_2^2$ in (33) then we get a discrete solitary wave solution to Eq. (27) as

$$u_{n,2}(t) = -\frac{1}{\beta} In \left(\frac{(\lambda^2 - 4\mu)c_1^2}{4\alpha\beta} \left(1 + csch^2 \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} d_1 \right) - tanh^2 \left(\frac{\sqrt{\lambda^2 - 4\mu}}{2} (d_1n + c_1t + \zeta) + tanh^{-1} \left(\frac{C_1}{C_2} \right) \right) \right) \right). \tag{34}$$

It is clear that our result (34) includes Liu et al.'s [26] result (41) as a special case.

Case 2: $\lambda^2 - 4\mu < 0$.

Substituting (31) along with $V_{n+1}(\xi_n)$ and $V_{n-1}(\xi_n)$ derived from (8b) into Eq. (30), clearing the denominator and equating the coefficients of $(G'(\xi_n)/G(\xi_n))^i(0 \le i \le 10)$ to zero, and solving the resulting algebraic system for $a_0, a_1, a_2, c_1, d_1, \lambda$, and μ , we get a solution set and the corresponding discrete trigonometric function traveling wave solution to Eq. (27) as follows:

$$\left\{ a_0 = \frac{-(\alpha\beta + c_1^2\mu)}{\beta} - \frac{c_1^2(\lambda^2 - 4\mu)}{4\beta} \csc^2\left(\frac{\sqrt{4\mu - \lambda^2}}{2}d_1\right), \quad a_1 = -\frac{\lambda c_1^2}{\beta}, \quad a_2 = -\frac{c_1^2}{\beta} \right\},$$
(35)

$$u_{n,3}(t) = -\frac{1}{\beta} \ln \left(\frac{(\lambda^{2} - 4\mu)c_{1}^{2}}{4\alpha\beta} \left(1 - \csc^{2}\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}d_{1}\right) + \left(\frac{-c_{1}\sin\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\xi_{n}\right) + c_{2}\cos\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\xi_{n}\right)}{c_{1}\cos\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\xi_{n}\right) + c_{2}\sin\left(\frac{\sqrt{4\mu - \lambda^{2}}}{2}\xi_{n}\right)} \right)^{2} \right) \right),$$
(36)

where $\xi_n = d_1 n + c_1 t + \zeta$, C_1 and C_2 are arbitrary constants.

Remark 5. In particular, if we take $C_2 \neq 0$, $C_1^2 < C_2^2$ in (36) then we obtain a discrete periodic wave solution to Eq. (27) as

$$u_{n,4}(t) = -\frac{1}{\beta} \ln \left(\frac{(\lambda^2 - 4\mu)c_1^2}{4\alpha\beta} \left(1 - \csc^2\left(\frac{\sqrt{4\mu - \lambda^2}}{2} d_1 \right) + \cot^2\left(\frac{\sqrt{4\mu - \lambda^2}}{2} (d_1n + c_1t + \zeta) + \tan^{-1}\left(\frac{C_1}{C_2} \right) \right) \right) \right). \tag{37}$$

We also note that many solutions obtained in Liu et al.'s [26] work can be easily recovered from our solutions (36) and (37) with appropriate choices of the parameters.

Case 3: $\lambda^2 - 4\mu = 0$.

Substituting (31) along with $V_{n+1}(\xi_n)$ and $V_{n-1}(\xi_n)$ derived from (8c) into Eq. (30), clearing the denominator and equating the coefficients of $(G'(\xi_n)/G(\xi_n))^i(0 \le i \le 10)$ to zero, and solving the resulting algebraic system for a_0, a_1, a_2, c_1, d_1 , and λ , we get the solution sets and the corresponding discrete rational function traveling wave solutions to Eq. (27) as follows:

$$\left\{ a_0 = -\alpha + \frac{1}{4} a_2 \left(\lambda^2 - \frac{4}{d_1^2} \right), \quad a_1 = \lambda a_2, \quad c_1 = \mp i \sqrt{\beta a_2} \right\}, \tag{38}$$

$$u_{n,5}^{\mp}(t) = -\frac{1}{\beta} \ln \left(\frac{a_2}{\alpha} \left(\frac{C_1^2}{(C_1(d_1n \mp i\sqrt{\beta a_2}t + \zeta) + C_2)^2} - \frac{1}{d_1^2} \right) \right), \tag{39}$$

where C_1 and C_2 are arbitrary constants.

Remark 6. We also observe that the rational solutions (39) are presented here for the first time and they do not appear in Liu et al. [26].

4. Conclusion

Using the (G'/G)-expansion method, we have successfully derived various families of discrete exact solutions to the DNSE and the TLE. Some of these solutions are found for the first time. The obtained results with more free parameters include most of the solutions in the open literature as special cases. As a result, the power of the employed method is confirmed. We assured the correctness of the obtained solutions by putting them back into the original equation with the aid of MATH-EMATICA, it provides an extra measure of confidence in the results. We predict that the (G'/G)-expansion method will be a promising method for investigating exact analytic solutions to NDDEs.

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